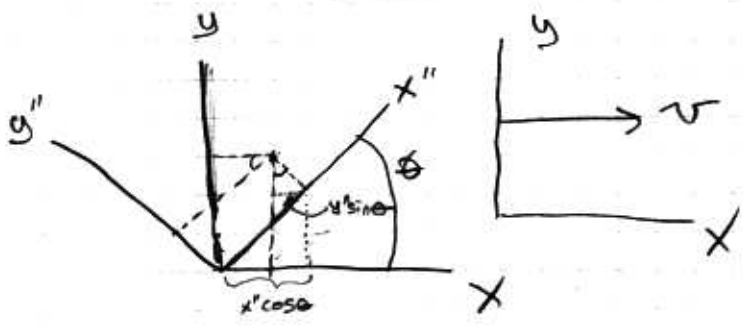


1



a) 
$$\begin{aligned} X &= x'' \cos \theta - y'' \sin \theta \\ Y &= x'' \sin \theta + y'' \cos \theta \end{aligned} \Rightarrow \begin{aligned} x'' &= X \cos \theta + Y \sin \theta \\ y'' &= -X \sin \theta + Y \cos \theta \end{aligned}$$

So 
$$R^{\alpha''} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \theta & \sin \theta & 0 \\ 0 & -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Row  $\alpha''$   
Col  $\beta$

b) THINK... THINK...

c) 
$$\Lambda^{\alpha''}_{\beta'} = R^{\alpha''} \gamma \Lambda^{\gamma}_{\beta'} = \Lambda^{\gamma}_{\beta'} R^{\alpha''}_{\gamma}$$

d) CAN DO MATRIX MULT HERE, IF WE ARE CAREFUL

THIS IS THE ORDERING FOR MATRIX MULT, BUT BOTH SUM EXPRESSIONS ARE RIGHT

$$\Lambda^{\alpha''}_{\beta'} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \theta & \sin \theta & 0 \\ 0 & -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \gamma & \gamma v & 0 & 0 \\ \gamma v & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\Lambda^{\alpha''}_{\beta'} = \begin{bmatrix} \gamma & \gamma v & 0 & 0 \\ \gamma v \cos \theta & \gamma \cos \theta & \sin \theta & 0 \\ -\gamma v \sin \theta & -\gamma \sin \theta & \cos \theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Row  $\alpha''$   
Column  $\beta'$

2

(a)  $u^{\alpha'} = \begin{bmatrix} \frac{1}{\sqrt{1-u^2}} \\ 0 \\ u \frac{1}{\sqrt{1-u^2}} \\ 0 \end{bmatrix}$

(b)  $u^{\alpha''} = \Lambda^{\alpha''}_{\beta'} u^{\alpha'} = \begin{bmatrix} \Lambda^0_0 u^0 + \Lambda^0_2 u^2 \\ \Lambda^1_0 u^0 + \Lambda^1_2 u^2 \\ \Lambda^2_0 u^0 + \Lambda^2_2 u^2 \\ 0 \end{bmatrix}$

$$= \begin{bmatrix} \frac{\gamma}{\sqrt{1-u^2}} + 0 \\ \frac{\gamma v \cos \theta}{\sqrt{1-u^2}} + \frac{u \sin \theta}{\sqrt{1-u^2}} \\ \frac{-\gamma v \sin \theta}{\sqrt{1-u^2}} + \frac{u \cos \theta}{\sqrt{1-u^2}} \\ 0 \end{bmatrix}$$

$$u^{\alpha''} = \frac{1}{\sqrt{1-u^2}} \begin{bmatrix} \gamma \\ \gamma v \cos \theta + u \sin \theta \\ -\gamma v \sin \theta + u \cos \theta \\ 0 \end{bmatrix}$$

$$\gamma \equiv \frac{1}{\sqrt{1-v^2}}$$

(c)  $g_{\alpha\beta} u^{\alpha''} u^{\beta''} = \frac{1}{1-u^2} \left\{ -\gamma^2 + (\gamma v \cos \theta + u \sin \theta)^2 + (-\gamma v \sin \theta + u \cos \theta)^2 \right\}$

$$= \frac{1}{1-u^2} \left\{ -\gamma^2 + \gamma^2 v^2 \cos^2 \theta + u^2 \sin^2 \theta + \gamma v u \cos \theta \sin \theta + \gamma^2 v^2 \sin^2 \theta + u^2 \cos^2 \theta - \gamma v u \cos \theta \sin \theta \right\}$$

$$= \frac{1}{1-u^2} \left\{ -\gamma^2 + \gamma^2 v^2 + u^2 \right\}$$



A260 MW#3

(3)

$$\frac{u}{w} = \frac{u}{w} = \frac{1}{1-u^2} \left\{ \frac{v^2-1}{1-v^2} + u^2 \right\} = \frac{u^2-1}{1-u^2} = \textcircled{-1}$$

WHEEL

3

(a)

$$300 \text{ km} = \int_{R_{\oplus}}^{R_{\oplus} + \Delta r} ds \quad dt=0$$

$$ds^2 = -\left(1 - \frac{2GM}{r}\right) dt^2 + \left(1 + \frac{2GM}{r}\right) dr^2$$

$$= \int_{R_{\oplus}}^{R_{\oplus} + \Delta r} \left(1 + \frac{2GM}{r}\right)^{1/2} dr \approx \int_{R_{\oplus}}^{R_{\oplus} + \Delta r} \left(1 + \frac{GM}{r}\right) dr$$

$$= \Delta r + GM \left[ \ln \frac{R_{\oplus} + \Delta r}{R_{\oplus}} \right]$$

$$\ln(1+x) \approx x - \frac{x^2}{2}$$

$$300 \text{ km} \approx \Delta r + \frac{\Delta r}{R_{\oplus}}$$

$$\Delta r = 300 \text{ km} - \frac{\Delta r GM}{R_{\oplus}} \approx 300 \text{ km} - \frac{300 \text{ km}}{R_{\oplus}} GM$$

DIFF IN r CORRD

$$\Delta r = 300 \text{ km} - \frac{300 \text{ km}}{6378 \text{ km}} \left( \frac{(6.67 \times 10^{-11} \frac{\text{m}^3}{\text{kg} \cdot \text{s}^2})}{(3 \times 10^{24} \text{ kg})^2} \right)$$

$$(5.972 \times 10^{24} \text{ kg})$$

$$\Delta r - 300 \text{ km} = -2.61 \times 10^{-4} \text{ m}$$

THAT'S PRETTY SMALL!!!

(b)

$$d\tau = \sqrt{-ds^2} = \left(1 - \frac{2GM}{r_{\oplus} c^2}\right)^{1/2} dt \quad \text{FOR CONST } r, \theta, \phi$$

$$\frac{d\tau}{dt} = \left(1 - \frac{2GM}{R_{\oplus} c^2}\right)^{1/2} \approx 1 - \frac{GM}{R_{\oplus} c^2} = \boxed{1 - 7 \times 10^{-10}}$$



$$\textcircled{c} \quad \frac{d\tau}{dt} = \left(1 - \frac{2GM_0}{(1\text{AU})c^2}\right)^{1/2} \approx 1 - \frac{GM_0}{(1\text{AU})c^2}$$

$$M_0 = 2 \times 10^{30} \text{ kg}$$

$$1 \text{ AU} = 1.5 \times 10^{11} \text{ m}$$

$$\frac{d\tau}{dt} = 1 - 10^{-8}$$

SUN'S TIME  
DILATION IS (MUCH)  
MORE SIGNIFICANT,  
BUT EVEN THAT'S  
NOT SAYING MUCH...

$$\boxed{4} \text{ HAZLE 6.6} \quad \text{NOTE: } \cosh^2 \alpha - \sinh^2 \alpha = 1$$

$$\textcircled{a} \quad dt = \left(\frac{c}{g} + \frac{x'}{c}\right) \cosh\left(\frac{gt'}{c}\right) \frac{g}{c} dt' + \frac{dx'}{c} \sinh\left(\frac{gt'}{c}\right)$$

$$dx = c \left(\frac{c}{g} + \frac{x'}{c}\right) \sinh\left(\frac{gt'}{c}\right) \frac{g}{c} dt' + dx' \cosh\left(\frac{gt'}{c}\right)$$

$$c^2 dt^2 = c^2 (dt')^2 \left[ \left(\frac{c^2}{g^2} + \frac{2x'}{g} + \frac{(x')^2}{c^2}\right) \frac{g^2}{c^2} \cosh^2\left(\frac{gt'}{c}\right) \right] + (dx')^2 \sinh^2\left(\frac{gt'}{c}\right)$$

$$dx^2 = c^2 (dt')^2 \left[ \left(\frac{c^2}{g^2} + \frac{2x'}{g} + \frac{(x')^2}{c^2}\right) \frac{g^2}{c^2} \sinh^2\left(\frac{gt'}{c}\right) \right] + (dx')^2 \cosh^2\left(\frac{gt'}{c}\right)$$

$$-c^2 dt^2 + dx^2 = -c^2 (dt')^2 \left(\frac{c^2}{g^2} + \frac{2x'}{g} + \frac{(x')^2}{c^2}\right) \frac{g^2}{c^2} + (dx')^2$$

$$\boxed{ds^2 = -g^2 (dt')^2 \left(\frac{c}{g} + \frac{x'}{c}\right)^2 + (dx')^2} \quad + (dy')^2 + (dz')^2$$

⑥

FOR SOMETHING AT REST IN THIS FRAME,  $dx' = 0$

$$\text{THEN} \quad \frac{dx}{dt} = \frac{c \left(\frac{c}{g} + \frac{x'}{c}\right) \sinh\left(\frac{gt'}{c}\right) \frac{g}{c} dt'}{\left(\frac{c}{g} + \frac{x'}{c}\right) \cosh\left(\frac{gt'}{c}\right) \frac{g}{c} dt'}$$

$$\frac{dx}{dt} = c \frac{\sinh\left(\frac{gt'}{c}\right)}{\cosh\left(\frac{gt'}{c}\right)}$$

$$\sinh \alpha = \frac{e^{\alpha} - e^{-\alpha}}{2}$$

$$\cosh \alpha = \frac{e^{\alpha} + e^{-\alpha}}{2}$$

FOR  $\alpha$  SMALL:

$$\sinh \alpha \approx \frac{1 + \alpha - | + \alpha}{2} \approx \alpha$$

$$\cosh \alpha \approx \frac{1 + \alpha + 1 - \alpha}{2} \approx 1$$

$$\boxed{\frac{dx}{dt} = gt'}$$

HEY, UNIFORM ACCEL

(IF  $t' \approx t$ , WHICH IT DOES IN THIS APPROX IF YOU SET  $x'=0$ )

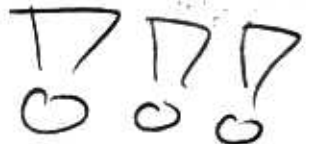
(C)

$$\frac{d\tau(x'=h)}{d\tau(x'=0)} = \frac{+g(dt')\left(\frac{c}{g} + \frac{h}{c}\right)}{+g(dt')\left(\frac{c}{g}\right)}$$

$$\boxed{\frac{d\tau(x'=h)}{d\tau(x'=0)} = 1 + \frac{gh}{c^2}}$$

JUST LIKE  
STATIC WEAK-FIELD  
FOR UNIFORM  
GRAV FIELD

$$\Phi = gx$$



5 PARTICLE G.13

S. W. F. METRIC w/  $\Phi = gz$ :  $ds^2 = -(1 + \frac{2gz}{c^2})(cdt)^2 + (1 - \frac{2gz}{c^2})dz^2$   
 $(dx=dy=0)$

OBSERVER 2:  $dz=0$   
 $z=0$  ← CHOOSE  
 $t$  ←  $t$  COORD @ END OF EXPERIMENT

$$CT = C\hat{\tau}_2 = \int_0^t \sqrt{-ds^2} = \int_0^t c dt = ct$$

↑  
TIME ELAPSED FOR  $\hat{\tau}_2$

$$T = \hat{\tau}_2 = t \quad \text{YAY!}$$

THIS IS THE REASON FOR THE  $z=0$  CHOICE; MAKES COORDINATES SIMPLER

$\hat{\tau}_1$ : UP:  $z = v_0 t - \frac{1}{2} g t^2$   
 DOWN:  $z = h - \frac{1}{2} g t^2$

UP:  $h = v_0 \left(\frac{T}{2}\right) - \frac{1}{2} g \left(\frac{T}{2}\right)^2 \Rightarrow$  REACHES  $z=h$   
 @  $t = \frac{T}{2}$

$$h = \frac{v_0 T}{2} - \frac{g T^2}{8}$$

DOWN:  $0 = h - \frac{1}{2} g \left(\frac{T}{2}\right)^2$   
 $= h - \frac{g T^2}{8} \Rightarrow$

$$h = \frac{g T^2}{8}$$

$$\frac{g T^2}{8} = \frac{v_0 T}{2} - \frac{g T^2}{8}$$

$$\frac{g T^2}{4} = \frac{v_0 T}{2}$$

$$v_0 = \frac{g T}{2}$$

NO SURPRISE...

$$v = v_0 - gt$$

$$v = 0 \text{ @ } t = \frac{T}{2} \Rightarrow$$

WAY UP:  $z = \frac{gT}{2}t - \frac{1}{2}gt^2$

$dz = \left(\frac{gT}{2} - gt\right) dt$        $dz = \left(\frac{gT}{2c} - \frac{gt}{c}\right) c dt$

$dz^2 = \left(\frac{g^2 T^2}{4c^2} - \frac{g^2 t T}{c^2} + \frac{g^2 t^2}{c^2}\right) c^2 dt^2$

$\frac{c\tau_1}{2} = \int_0^{T/2} \sqrt{-ds^2} = \int_0^{T/2} \left[ \left(1 + \frac{2gz}{c^2}\right) c^2 dt^2 - \left(1 - \frac{2gz}{c^2}\right) dz^2 \right]^{1/2}$

$\frac{c\tau_1}{2} = \int_0^{T/2} c dt \left[ \left(1 + \frac{g^2 T t}{c^2} - \frac{g^2 t^2}{c^2}\right) - \left(1 - \frac{g^2 T t}{c^2} + \frac{g^2 t^2}{c^2}\right) \left(\frac{g^2 T^2}{4c^2} - \frac{g^2 t T}{c^2} + \frac{g^2 t^2}{c^2}\right) \right]^{1/2}$

$\frac{c\tau_1}{2} = \int_0^{T/2} dt \left[ 1 + \frac{g^2 T t}{c^2} - \frac{g^2 t^2}{c^2} - \frac{g^2 T^2}{4c^2} + \frac{g^2 t T}{c^2} - \frac{g^2 t^2}{c^2} + O\left(\frac{1}{c^4}\right) \right]^{1/2}$

$= \int_0^{T/2} dt \left[ 1 + \frac{2g^2 T t}{c^2} - \frac{2g^2 t^2}{c^2} - \frac{g^2 T^2}{4c^2} \right]^{1/2} \approx \int_0^{T/2} dt \left[ 1 + \frac{g^2 T t}{c^2} - \frac{g^2 t^2}{c^2} - \frac{g^2 T^2}{8c^2} \right]$

$= \left[ t + \frac{g^2 T t^2}{2c^2} - \frac{g^2 t^3}{3c^2} - \frac{g^2 T^2 t}{8c^2} \right]_0^{T/2} = \frac{T}{2} + \frac{g^2 T^3}{8c^2} - \frac{g^2 T^3}{24c^2} - \frac{g^2 T^3}{16c^2}$

$\tau_1 = T \left( 1 + \frac{g^2 T}{4c^2} - \frac{g^2 T^2}{12c^2} - \frac{g^2 T^2}{8c^2} \right) = \boxed{T \left( 1 + \frac{g^2 T^2}{24c^2} \right)}$  ← FREE FALLING CLOCK

OBSERVER 3:  $z = vt$  ← SAME h

WAY UP  $h = v \frac{T}{2} = \frac{gT^2}{8}$

$v = \frac{gT}{4}$

$z = \frac{gT}{4}t$        $dz = \frac{gT}{4} dt$

$\frac{c\tau_3}{2} = \int_0^{T/2} \sqrt{-ds^2} = \int_0^{T/2} \left[ \left(1 + \frac{2gz}{c^2}\right) c^2 dt^2 - \left(1 - \frac{2gz}{c^2}\right) dz^2 \right]^{1/2}$



$$\frac{c\tau_3}{2} = \int_0^{T/2} c dt \left[ \left( 1 + \frac{g^2 T t^2}{2c^2} \right) - \left( 1 - \frac{g^2 T t^2}{2c^2} \right) \frac{g^2 T^2}{16c^2} \right]^{1/2}$$

$$= \int_0^{T/2} c dt \left[ 1 + \frac{g^2 T t^2}{2c^2} - \frac{g^2 T^2}{16c^2} + \mathcal{O}\left(\frac{1}{c^4}\right) \right]^{1/2}$$

$$\frac{\tau_3}{2} \approx \int_0^{T/2} dt \left[ 1 + \frac{g^2 T t^2}{4c^2} - \frac{g^2 T^2}{32c^2} \right] = \left[ t + \frac{g^2 T t^3}{8c^2} - \frac{g^2 T^2 t}{32c^2} \right]_0^{T/2}$$

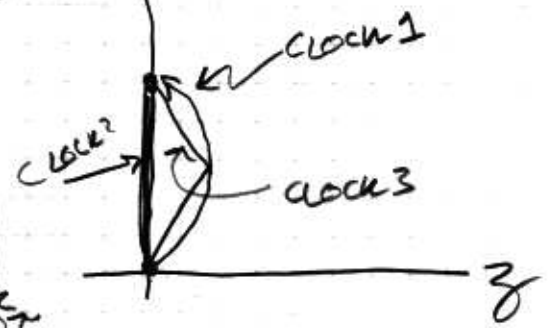
$$\frac{\tau_3}{2} = \frac{T}{2} + \frac{g^2 T^3}{32c^2} - \frac{g^2 T^3}{64c^2} = \frac{T}{2} \left( 1 + \frac{g^2 T^2}{32c^2} \right)$$

$$\tau_3 = T \left( 1 + \frac{g^2 T^2}{32c^2} \right)$$

LINEAR MOTION  
CLOCK

$\tau_1 > \tau_3 > \tau_2$   
FREE-FALLING CLOCK,  
EXPECT EXTREMAL  
PROPER TIME!

CLOSEST  
PATH TO C,  
THAN  $\tau_2$  IS



IF MOTION IS HORIZONTAL:  $z=0$ ,  $ds^2 = -dt^2 + dz^2 + dx^2$

ANALYSIS WILL LOOK JUST LIKE SR,  
SO CLOCK 2 (UNACCELERATED) WILL  
HAVE MAX PROPER TIME  $\Rightarrow$  THIS  
LOOKS JUST LIKE THE TWIN  
PARADOX  $\nabla$   
G